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					MARLYN COBALT SPECIFICATIONS
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Atmos is a leader in geospatial drone

technologies. With a deep awareness of our future challenges in resources, population growth, and climate change, our team of dedicated problem solvers are working hard to help you plan with efficiency, accuracy, and precision. We specialise in high quality surveying and mapping VTOL drones, capable of operating in the roughest weather conditions.

Our flagship product Marlyn Cobalt is proudly designed, engineered, tested, and manufactured from our headquarters in Leiden, The Netherlands.



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## Marlyn Specifications

#### OPERATION

Take-off & landing area	2 x 2 m [7 x 7 ft] required		
Set-up time	5 minutes		
Automatic Flight	Fully automatic flight execution of preprogram control by user.	mmed mission; Automatic flight with position	
Take-off & landing	Automatic takeoff, Assisted landing	Weather dependent	
Cruise speed	65 km/h [40 mph]	Indicated Airspeed	
Wind resistance	Take off: 45 km/h [28 mph] / Cruise: 55 km/	h [34 mph] / Landing: 45 km/h [28 mph]	
Max flight time	50 mins Dependent on environmental cond		
Pre-flight checklist	Yes (integrated in Navigator)		
Temperature range	-10°C to +40°C [14°F to 104°F]	Above 35°C operating restrictions apply	
GCPs	Not required with optional PPK module		
Max. operating altitude	5000m [16,000 ft] above mean sea level (hi	gh altitude propellers required above 1800m)	
Ingress protection	IP54 — It is not recommended to fly in fog, r	rain and snow	

#### SAFETY

Safety Lights	Lights indicate Marlyn's status. When they are off Marlyn is safe to approach		
Return to home	Single tap function returns Marlyn to home		
Low Battery	Automatic return to home (configurable) Emergency Controls Possib		
Lost Link	Automatic return to home (configurable)		
Geofence Both horizontal and vertical (configurable)			
System Diagnostics Built-in comprehensive pre-flight and in-flight checks ensure a safe flight		re a safe flight	
Avoidance Maneuvres Pause, abort mission, perform an upward, sideward, or downward maneuvre. Resu		wnward maneuvre. Resume if clear	
Manual flight override Intuitively fly Marlyn to safety in both airplane and helicopter mode		er mode	
Emergency Landing	Immediately land Marlyn in helicopter mode in case of app	roaching aircraft	

#### SOFTWARE

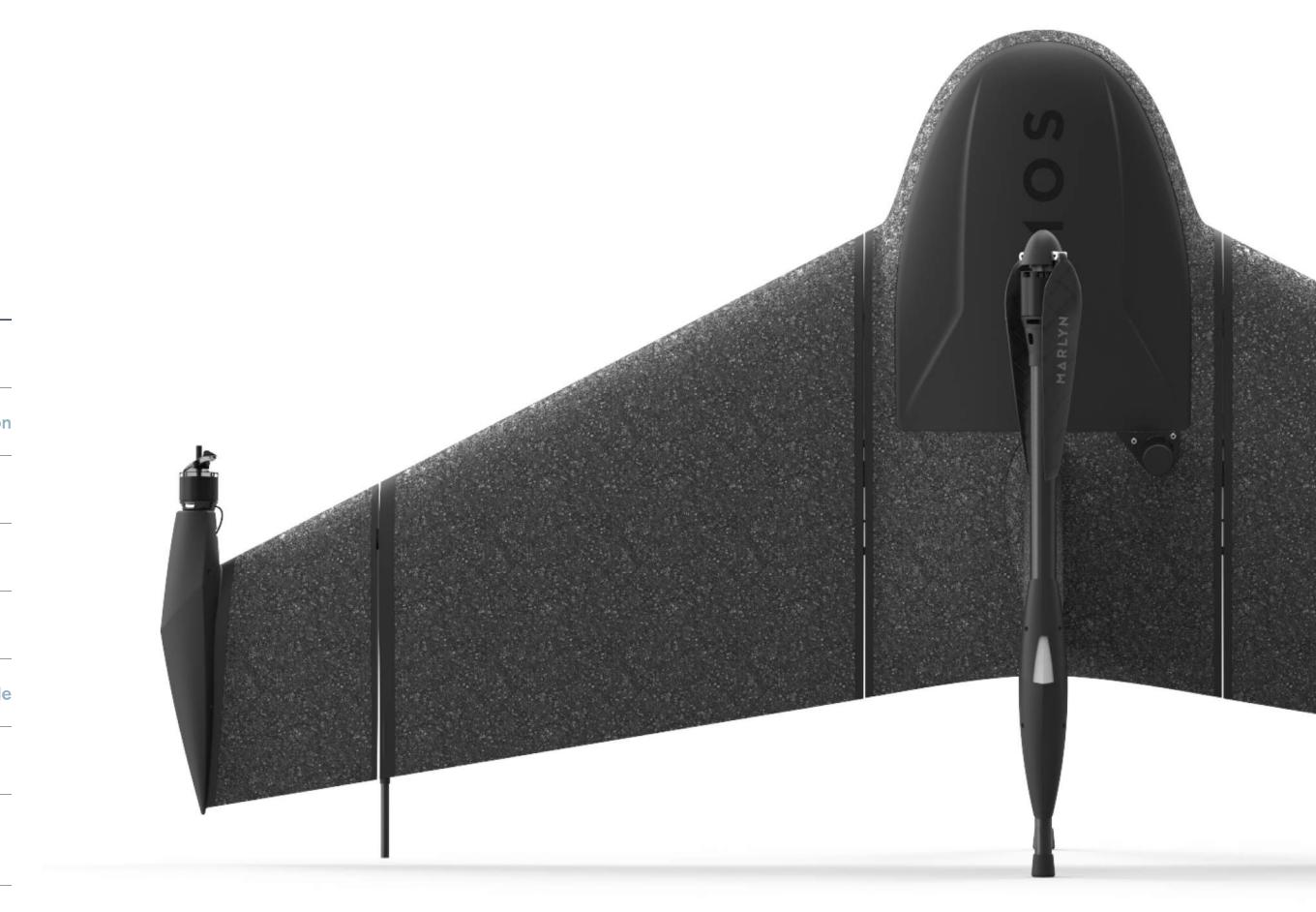
Flight planning + Processing	Navigator, Geotagger (In-house developed)	Include
System Requirements	Windows. CPU: Quad core 1.20GHz (i5-7Y57 Kab Graphics: Intel HD Graphics 615 or equivalent; HD	
Flight Operation	Automatic	<b>Emergency Controls Possibl</b>
Input files	.KML, .KMZ, .GeoTIFF, .MBTiles, .WMTS	
Mapping Options	Polygon, Linear Corridor (Time based triggering, pos	sition based triggering)

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## Marlyn Specifications

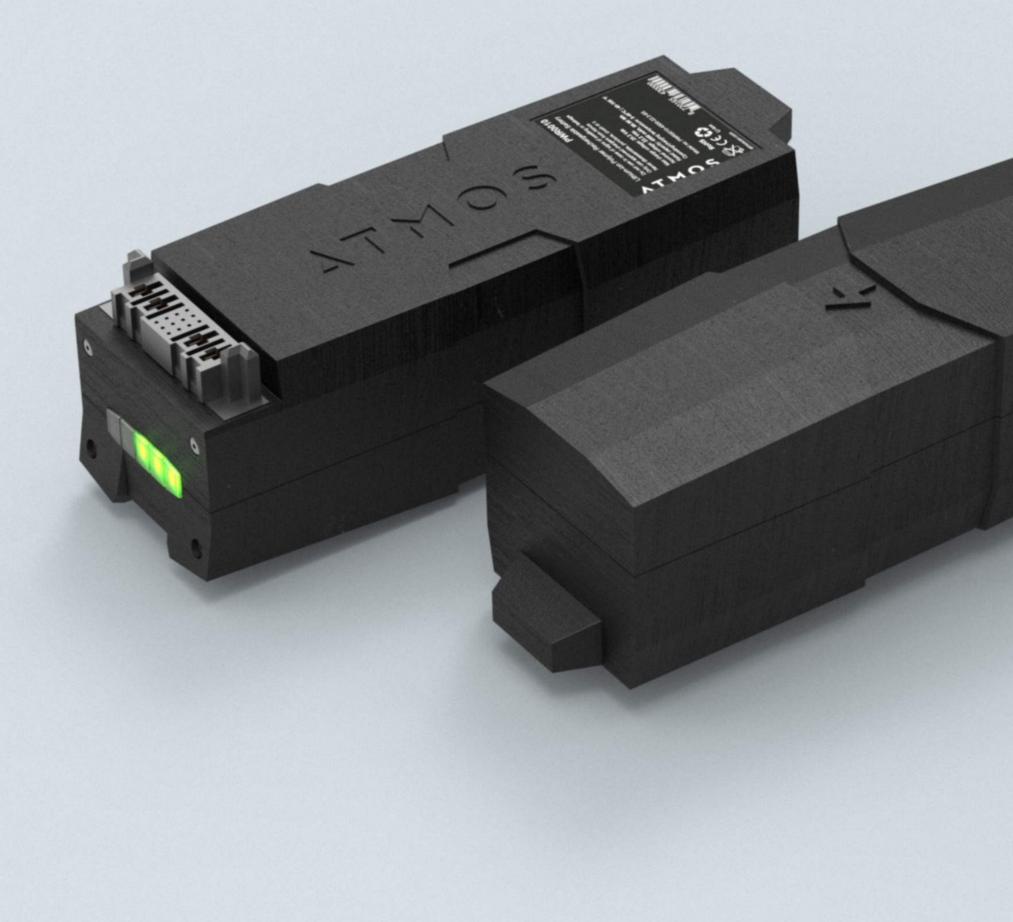
#### HARDWARE

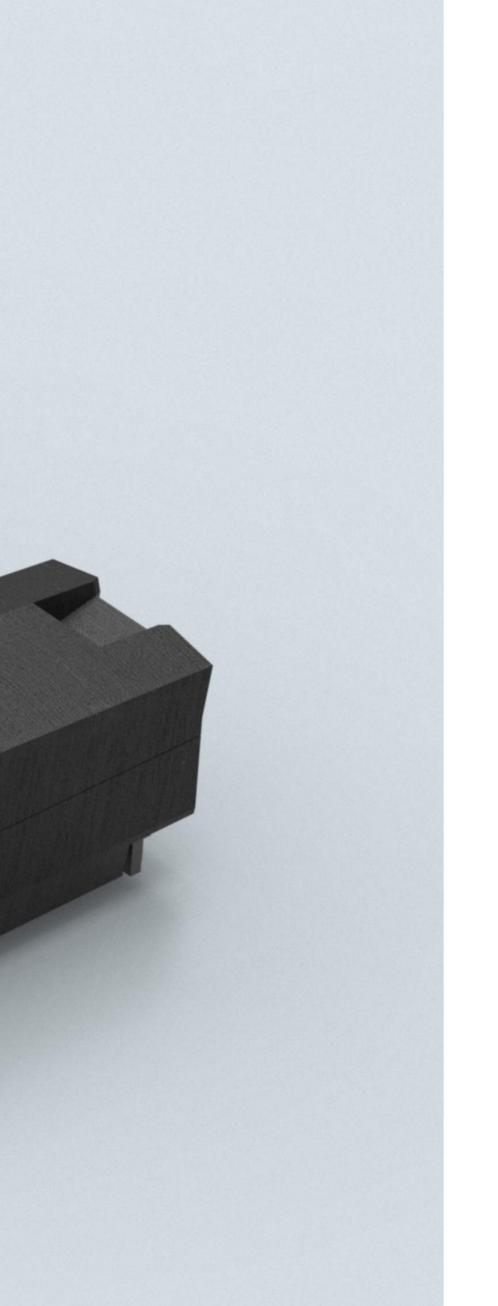
Drone type	Hybrid — VTOL (Vertical Take-Off and Landing) & fixed	Hybrid — VTOL (Vertical Take-Off and Landing) & fixed-wing	
Max takeoff weight	6.4 kg [14.1 lbs] (Including batteries)	6.4 kg [14.1 lbs] (Including batteries) Standard Configuration	
Wingspan	1.6 m [5.2 ft] (With detachable wings for easy transpo	ortation in Marlyn's backpack)	
Built in safety lights 2 Navigation lights, 2 Anti-collision lights — Over 1km [0.6 miles] of visibility		[0.6 miles] of visibility	
Motors	4 electric motors	4 electric motors	
Telemetry link range	Default 7 km [4.3 miles]	Alternative configurations possible	
RC link range	Default 1 km [0.6 miles] (Alternative configurations possible)		
Included accessories		Backpack, 4 batteries, battery charger, remote control, Navigator modem, in-field maintenance kit, battery case, Wind anemometer, cables, spare parts	
Materials	Carbon fiber frame surrounded with durable structural	Carbon fiber frame surrounded with durable structural EPP	
RC Battery	3.7V 5000mAh Lithium-polymer battery. 8hrs Battery Life, 2.5hrs charge time. USB-C Charging. May be charged while in use.		





## **Dual Smart Battery System**



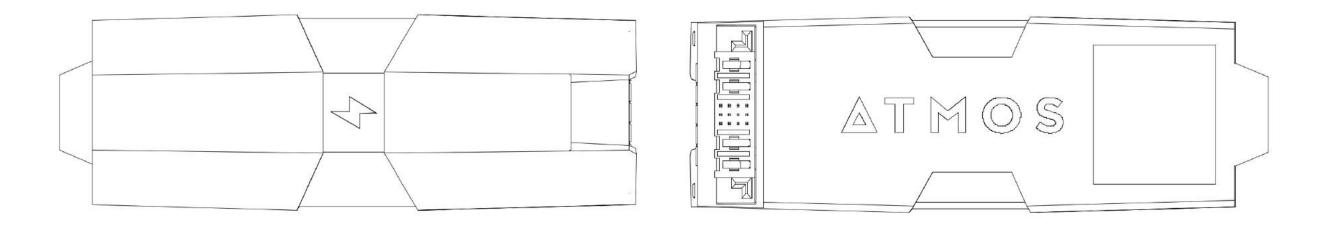


THE BATTERY SYSTEM IS A CRITICAL COMPONENT FOR SAFE OPERATION OF SURVEYING DRONES.

> It also has a direct influence on the flight performance. To further increase the operational efficiency and reliability of Marlyn, Atmos' engineering team designed a dual smart battery system that results in redundancy, peace-of-mind, and durability.



## Smarter atteries



#### **SPECIFICATIONS**

Type of battery	Lithium-polymer battery	1 set (2 batteries) required to fly
Battery capacity	4500 mAh (99.9 Wh)	9000 mAh per battery set
Weight	670 g [24 oz] per battery	
Status lights	Transparent button with 5 imbedded LED status	lights
Size (LxHxW)	170 x 58 x 58 mm [6.7 x 2.3 x 2.3 in]	
Charging Time	30 - 60 min (60 min per battery set, when comp	bletely discharged)
Air Travel Compliance	Meets standard conditions for air travel in carry-o	on luggage below 100Wh

#### PEACE OF MIND

Battery Management System (BMS for optimal flight performance. Both batteries are closely monitored in terms of remaining energy capacity, voltage, and temperature. Complying with airline carryon luggage regulations making it easy to transport from one job to another

#### REDUNDANCY

Each battery acts as a failsafe to the other to maximize reliability ensuring safe operation without any disruptions. The two batteries are used in parallel to create one integrated power system. Marlyn's smart power board can recognize any unexpected inconsistencies and initiate its predefined safety routine to land automatically.

#### DURABILITY

After 300 charges, you still have 80-90% capacity remaining. The strengthened shell with rugged connectors eliminates potential failure points for increased safety and ease of use.



# Marlyn's Backpack

#### SPECIFICATIONS

Size	75cm x 45cm x 85cm
Weight	Backpack 11 kg + Marlyn +/- 17 kg + accessories +/- 19 kg
Material	Nylon exterior, protective foam interior
Capacity	Marlyn, 4 sets of batteries, laptop, pole/total station, extra payload module, telemetry module, RC module, and small accessories
Travel	Handled as standard luggage by airlines
Water protection	Water proof vinyl Base
Straps	Padded shoulder straps with waist belt





# Why PPK?

CAPTURE DATA

FEWER TO NO GCP'S REQUIRED

FLIGHT PLANNING

Capturing high-resolution images with ultra-precise geotagging is crucial when converting aerial imagery into accurate point clouds.

When looking at the different options to increase the accuracy, Ground Control Points (GCPs) is the least effective method as it requires a lot of time in the field and more complex post-processing which results in higher costs in the end. By choosing PPK, the accuracy of your image geotags is drastically improved. Data recorded by the PPK module is augmented by satellite corrections resulting in ultra-precise geotags. This ensures high precision datasets without the use of GCP's.

These accuracies can be achieved with any PPK enabled Marlyn with a properly located base station or CORS network.



# Accuracy and Efficiency

### REDUCE TIME AND COSTS WITH A PPK- ENABLED MARLYN

- Absolute accuracy down to cm-level, with no realtime datalink required.
- High data quality and consistency over your complete project without laying out GCPs.
- High end Topcon PPK featuring multi-constellation, multi frequency all-in-view satellite tracking.



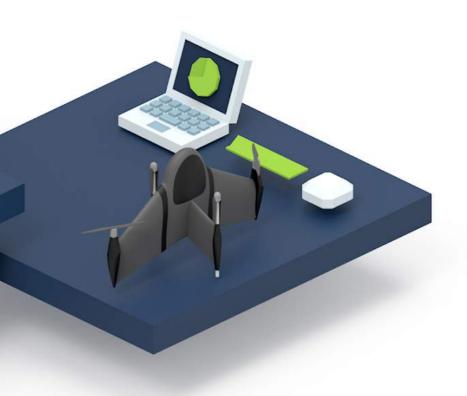
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### **PPK Benefits**



NO DIRECT DATA LINK REQUIRED. DATA COLLECTION TRACEABLE.

#### RTK



DIRECT DATA LINK REQUIRED. CANNOT RETRIEVE LOST DATA.

#### PPK VS. RTK

The two most common methods of GPS correction technology are Real Time Kinematic (RTK) and Post Processing Kinematic (PPK).

RTK (Real Time Kinematic) relies on continuous link between a fixed GNNS base station (above a known point) and a GNSS rover on the UAV. During an RTK mission, the RTK module must stay connected to the base station while it's gathering data in order for the two-way communication to inform positioning.

Due to the long distances and obstructions between the drone and the base station, signals can be disrupted resulting in loss of correction data and a lower percentage of accurate camera positions in the flight.

PPK, on the other hand, processes the positioning information after the flight, not during. Data is logged in the aircraft and combined with data from the base station when the flight is completed. As a result, there is no risk of data or initialisation loss due to radio link disruptions. PPK drones therefore offer more flexibility in terms of how and where the drone is deployed.

Regarding the processing of the captured data, both technologies are similar, however PPK is more thorough as it traces back and forth through the data multiple times to give more comprehensive results.





#### UPGRADEABLE & MODULAR

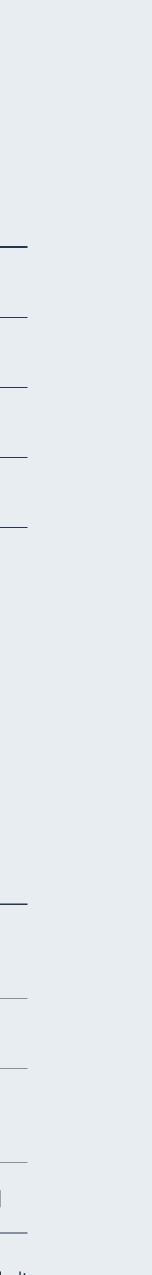
Marlyn's payloads are upgradable and swappable in minutes, no tools required! A variety of RGB and specialty camera modules are available to suit your project needs.



	Sony A7R IV	Sony A6100
Sensor Format	Full Frame	APS-C
Spectral bands	RGB	RGB
Pixel count	61 MP	24 MP
Lowest GSD	1.4 cm/px [0.6 in/px]	1.96 cm/px [0.8 in/px]

#### MULTISPECTRAL

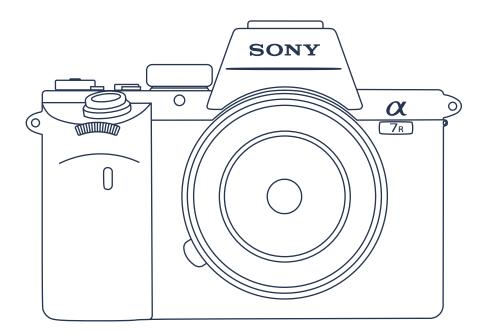
	RedEdge-P	<b>Altum PT</b> Multispectral EO Bands	Altum PT Thermal Band
Sensor Layout	5 individual sensors +1 panchromatic sensor	5 individual sensors +1 panchromatic sensor	FLIR LWIR
Spectral bands	RGB, Red Edge, Near-IR	RGB, Red Edge, Near-IR	8-14 μm
Pixel count	Spectral 1.6 + Panchromatic 5.1	Spectral 3.2 MP + Panchromatic 12MP +	160 x 120 Pixels
Lowest GSD	2.6 cm/px [1 in/px]	1.69 cm/px [0.7 in/px]	21.3 cm/px [8.4 in/px]





### CAPTURE THE LARGEST AREAS

Sony's 61 Megapixel Full-Frame sensor meets Zeiss' renowned 21mm lens, offering cm-level imagery and a whopping 350Ha coverage per flight. The A7RIV makes even the biggest areas part of your everyday offering.



#### SPECIFICATIONS

Sensor Format	Full Frame
Pixel count	61 MP
Focal length	21 mm
Shutter type	Focal Plane Shutter
Trigger Frequency	0.8 Hz (at full resolution)
Vertical Accuracy	3 cm [1.2 in] **
Horizontal Accuracy	1 cm [0.4 in]**

Spectral bands	RGB
Sensor size	35.7 x 23.8 mm
Pixels array	9504 x 6336 px
Pixel pitch	3.76 μm
Integration	Powered and controlled by Marlyn
Vertical field of view	59° (-10.5°, +48.5°)
Horizontal field of view	۶ 81°

### RESULTS

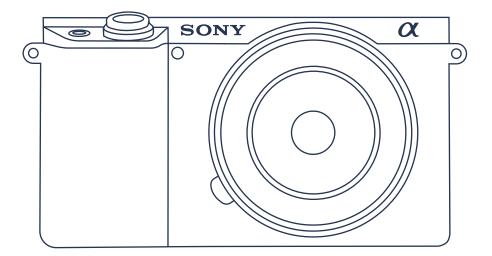
GSD	Altitude	Coverage*	Frontal Overlap* No wind condition
1.4 cm	80 m	200 ha	76%
[0.6 in]	[260 ft]	[500 ac]	
1.8 cm	100 m	250 ha	81%
[0.7 in]	[330 ft]	[600 ac]	
2.2 cm	120 m	300 ha	84%
[0.9 in]	[400 ft]	[750 ac]	
3.6 cm	200 m	500 ha	90%
[1.4 in]	[650 ft]	[1200 ac]	
5.4 cm	300 m	700 ha	94%
[2.1 in]	[990 ft]	[1700 ac]	





### AFFORDABLE AND ACCURATE

A great camera for an even greater price! The Sony A6100 is a 24 MP sensor which provides GSD results as low as 1.96 cm. Fitted with a Meike 12mm wide-angle lens, it also provides fantastic coverage and is great for capturing oblique features for 3D mapping of urban sites.



#### SPECIFICATIONS

Sensor Format	APS-C
Pixel count	24 MP
Focal length	12 mm
Shutter type	Focal Plane Shutter
Trigger Frequency	1 Hz (at full resolution)
Vertical Accuracy	4 cm [1.6 in]**
Horizontal Accuracy	2 cm [0.8 in]**

Spectral bands	RGB
Sensor size	23.5 x 15.6 mm
Pixels array	4000 x 6000 px
Pixel pitch	3.85 μm
Integration	Powered and controlled by Marlyn
Vertical field of view	67.4° (-7.7°, +49.7°)
Horizontal field of view	v 90°

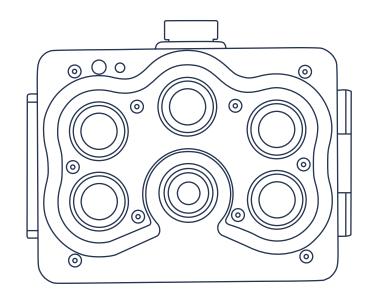
#### RESULTS

GSD	Altitude	Coverage*	Frontal Overlap* No wind condition
2.6 cm	80 m	250 ha	83%
[1 in]	[260 ft]	[620 ac]	
3.3 cm	100 m	300 ha	86%
[1.3 in]	[330 ft]	[740 ac]	
3.9 cm	120 m	350 ha	89%
[1.5 in]	[400 ft]	[870 ac]	
6.5 cm	200 m	650 ha	93%
[2.6 in]	[650 ft]	[1600 ac]	
9.8 cm	300 m	850 ha	95%
[3.9 in]	[990 ft]	[2100 ac]	



## MicaSense RedEdge-

The RedEdge-P is the newest industry-standard Multispectral camera, built-to-last with 5 spectral bands and a high-res panchromatic sensor. The RedEdge-P has the ability to generate accurate & repeatable plant health indices and highaccuracy RGB images in one flight.



#### **MULTISPECTRAL**

#### PANCHROMATIC

Spectral bands	RGB, Red Edge, Near-IR	171.5 - 1097.5 nm
Pixel count	1.6 MP	5.1 MP
Sensor size	4.73 x 4.2 mm	8.33 x 7.4 mm
Focal length	5.5 mm	10.3 mm
Pixel size	3.45 μm	3.45 μm
Output bit depth	12-bit	12-bit
Field of view	49.6° HFOV x 38.3° VFOV	44.5° HFOV x 37.7° VFOV

FOR

#### RESULTS

#### PANCHROMATIC

GSD	Altitude	Coverage*	Frontal Overlap**
2.6 cm	80 m	100 ha	83%
[1 in]	[260 ft]	[250 ac]	
3.3 cm	100 m	120 ha	87%
[1.3 in]	[330 ft]	[300 ac]	
3.9 cm	120 m	140 ha	89%
[1.5 in]	[400 ft]	[350 ac]	
6.6 cm	200 m	240 ha	93%
[2.6 in]	[650 ft]	[600 ac]	
9.8 cm	300 m	360 ha	96%
[3.9 in]	[990 ft]	[900 ac]	





## MicaSense Altum

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The Altum-PT is the most advanced Agricultural sensor system on the market today, capturing synchronized multispectral, thermal, and panchromatic data for plant health indices and RGB outputs at leaf-level resolutions.

	MULTISPECTRAL	THERMAL	PANCHROMATIC
Spectral bands	RGB, Red Edge, Near-IR	7.5 -13.5 μm	171.5 - 1097.5 nm
Pixel count	3.2 MP	320 x 256 Pixels	4112 x 3008 Pixels
Sensor size	7.12 x 5.33 mm	3.84 x 3.07 mm	14.18 x 10.37 mm
Focal Length	8 mm	4.5 mm	16.3 mm
Pixel size	3.45 μm	12 μm	3.45 μm
Output bit depth	12-bit	16-bit	12-bit
Field of view	48° HFOV x 36.8° VFOV	48° HFOV x 39° VFOV	46° HFOV x 35° VFOV

#### RESULTS

#### PANCHROMATIC

GSD	Altitude	Coverage*	Frontal Overlap**
1.7 cm	80 m	100 ha	82%
[0.7 in]	[260 ft]	[250 ac]	
2.1 cm	100 m	120 ha	86%
[0.8 in]	[330 ft]	[300 ac]	
2.5 cm	120 m	160 ha	88%
[1 in]	[400 ft]	[400 ac]	
4.2 cm	200 m	260 ha	93%
[1.7 in]	[650 ft]	[640 ac]	
6.4 cm	300 m	360 ha	95%
[2.5 in]	[990 ft]	[900 ac]	







sales@atmosuav.com www.atmousuav.com +31 (0) 88 028 6670 Hangaargebied Marinevliegkamp 356 2236ZZ Valkenburg (ZH) The Netherlands





